

Symmetric Indefinite Triangular Factorization Revealing the Rank Profile Matrix

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Context

Applications of symmetric Gaussian elimination

- Symmetric linear system solving
- Signature
- LLL: R factor of rational QR [Villard'12])

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Compared to unsymmetric Gaussian elimination

- Save a factor of 2 in time complexity
- Invariants specific to symmetric matrices (signature)

Motivation here

- `fsytrf`: finite field dense symmetric elimination in `fflas-ffpack`
- to be lifted for `LinBox` signature over \mathbb{Z}
- reduction to matrix product: $O(n^2 r^{\omega-2})$ and BLAS3
- investigate symmetric rank profile matrix and related pivoting

Outline

- 1 State of the art on symmetric factorizations
- 2 Rank profile and pivoting
- 3 Algorithms
- 4 The characteristic 2 case
- 5 Performance

Symmetric factorizations

Symmetric Decomposition

$$\begin{array}{|c|} \hline \mathbf{A} \\ \hline \end{array} = \begin{array}{|c|} \hline \mathbf{B} \\ \hline \end{array} \begin{array}{|c|} \hline \mathbf{B}^T \\ \hline \end{array}$$

Exists for

Field with sqrt &
Generic rank profile

Symmetric factorizations

Symmetric Decomposition

$$A = B B^T$$

$$A = L D L^T$$

Exists for

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Symmetric factorizations

Symmetric Decomposition

$$A = \begin{bmatrix} B \\ & B^T \end{bmatrix}$$

$$A = \begin{bmatrix} L \\ & D \\ & & L^T \end{bmatrix}$$

$$A = \begin{bmatrix} P \\ & L \\ & & D \\ & & & L^T \\ & & & & P^T \end{bmatrix}$$

$$A = \begin{bmatrix} P \\ & L \\ & & T \\ & & & L^T \\ & & & & P^T \end{bmatrix}$$

$$A = \begin{bmatrix} P \\ & L \\ & & Y \\ & & & L^T \\ & & & & P^T \end{bmatrix}$$

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Generic rank profile

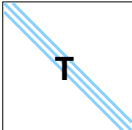
No $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ -like blocks

Any [Parlett-Reid 1970]
 T tridiagonal

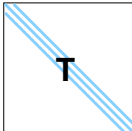
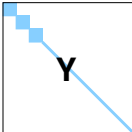
⋮

Any [Bunch-Kaufmann 1977]
 Y with 1×1 and 2×2 blocks

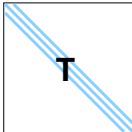

State of the art

Form	Properties		
	<p>[Parlett-Reid 1970] Diagonal Pivoting Iterative $\frac{2}{3}n^3$</p>	<p>[Bunch-Parlett 1971] Full pivoting Iterative $\frac{2}{3}n^3$</p>	<p>[Aasen 1971] Partial pivoting Iterative $\frac{1}{3}n^3$</p>

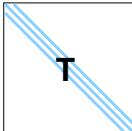
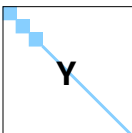
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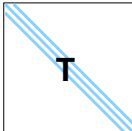
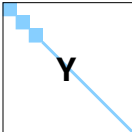
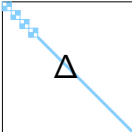
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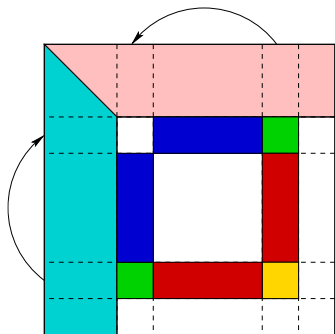
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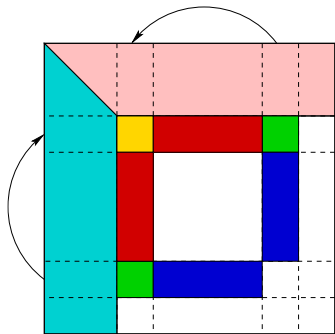
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	<p>Here</p> <p>Pivoting revealing the rank profile matrix</p> <p>Recursive for any matrix</p> <p>$O(n^2 r^{\omega-2})$ (gives $\frac{1}{3}n^3$ when $rank=n$ & $\omega=3$)</p>		

Symmetric pivoting



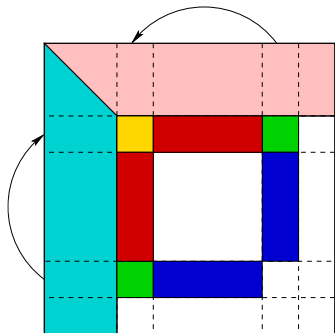
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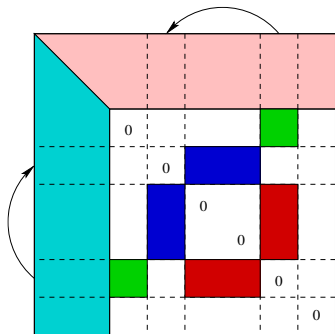
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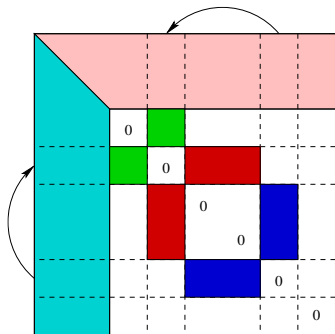
- Diagonal pivoting
 $\Rightarrow LDL^T$ with D diagonal

Symmetric pivoting



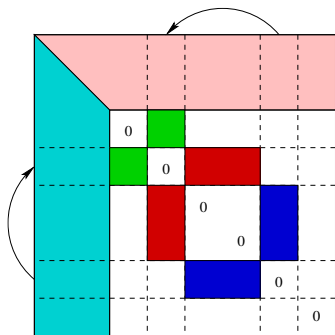
- Diagonal pivoting
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- Off-diagonal pivoting with zero diagonal

Symmetric pivoting



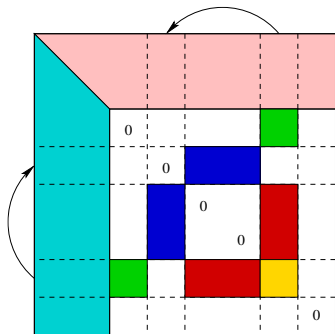
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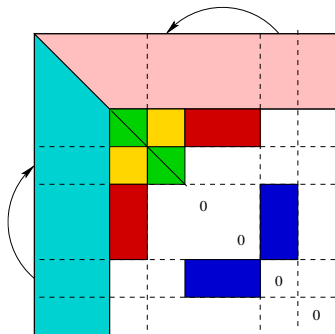
- Diagonal pivoting
 $\Rightarrow LDL^T$ with D diagonal
- Off-diagonal pivoting with zero diagonal
 $\Rightarrow L\Delta L^T$ with Δ block diagonal, 1×1
 or $2 \times 2 \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ blocks

Symmetric pivoting



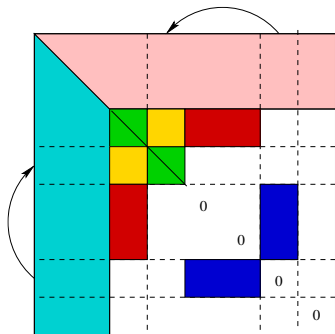
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- Off-diagonal pivoting with non-zero diagonal
 $\Rightarrow LDL^T$ with D diagonal
 \Rightarrow requires division by 2

The rank profile matrix

Rank Profiles

Given a matrix A of rank r :

Example

$$A = \begin{pmatrix} 0 & 0 & 0 & 2 \\ 3 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 \\ 5 & 0 & 0 & 0 \end{pmatrix}$$

The rank profile matrix

Rank Profiles

Given a matrix A of rank r :

- RRP (Row Rank Profile): first r linearly independent rows

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The rank profile matrix

Rank Profiles

Given a matrix A of rank r :

- RRP (Row Rank Profile): first r linearly independent rows
- CRP (Column Rank Profile): first r linearly independent columns

Example

$$A = \begin{pmatrix} \begin{pmatrix} 0 \\ 3 \\ 0 \\ 5 \end{pmatrix} & \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 0 \\ 4 \\ 0 \\ 0 \end{pmatrix} & \begin{pmatrix} 2 \\ 0 \\ 0 \\ 0 \end{pmatrix} \end{pmatrix}$$

The rank profile matrix

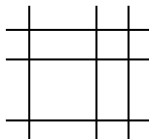
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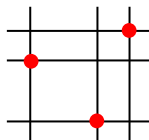
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RPM (Rank Profile Matrix)

The unique \mathcal{R}_A such that any pair of (i, j) -leading sub-matrix of \mathcal{R}_A and of A have the same rank.

Pivoting revealing the rank profile matrix (unsymmetric)

[D., P., Sultan. ISSAC'15.] *Computing the Rank Profile Matrix.*

Definition

$A = PLUQ$ reveals the rank profile matrix if $P \begin{bmatrix} I_r & \\ & 0 \end{bmatrix} Q = \mathcal{R}_A$

Search	Row perm.	Col. perm.	RowRP	ColRP	\mathcal{R}_A	Instance
Row order	Transposition	Transposition	★			[IMH82] [JPS13]
Col. order	Transposition	Transposition		★		[KG85] [JPS13]
Lexico.	Transposition	Transposition	★			[Sto00]
Lexico.	Transposition	Rotation	★	★	★	[DPS15]
Lexico.	Rotation	Rotation	★	★	★	[DPS15]
Rev. lex.	Transposition	Transposition		★		[Sto00]
Rev. lex.	Rotation	Transposition	★	★	★	[DPS15]
Rev. lex.	Rotation	Rotation	★	★	★	[DPS15]
Product	Rotation	Transposition	★			[DPS15]
Product	Transposition	Rotation		★		[DPS15]
Product	Rotation	Rotation	★	★	★	[DPS13]

Pivoting revealing the rank profile matrix (symmetric case)

Definition

$A = PL\Delta L^T P^T$ reveals the rank profile matrix \mathcal{R}_A if

$$P\Delta P^T = \text{Diag}(d_1, \dots, d_n)\mathcal{R}_A$$

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Pivoting revealing the rank profile matrix

- 1 Find pivot with minimal coordinates w.r.t.
 - lexicographic, reverse lexicographic or product order
- 2 Move it using cyclic rotations

Pivoting revealing the rank profile matrix (symmetric case)

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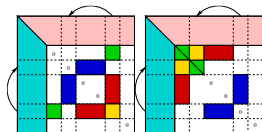
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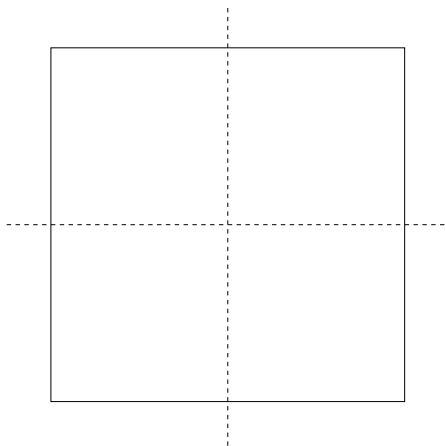
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- ⇒ Off-diagonal pivoting with non-zero diagonal
- ⇒ Requires division by 2.

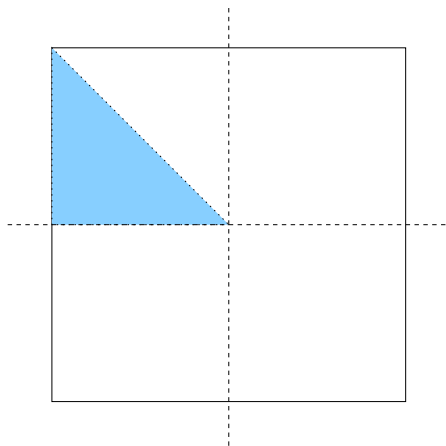


The recursive algorithm: full rank case



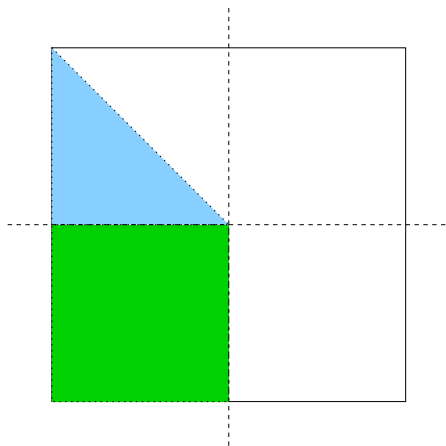
④ Split

The recursive algorithm: full rank case



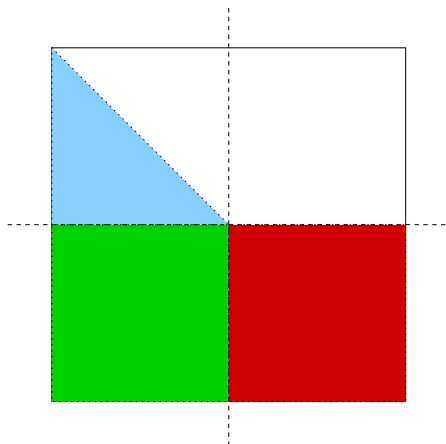
- 1 Split
- 2 Recursive call: $A_{11} = L_1 L_1^T$

The recursive algorithm: full rank case



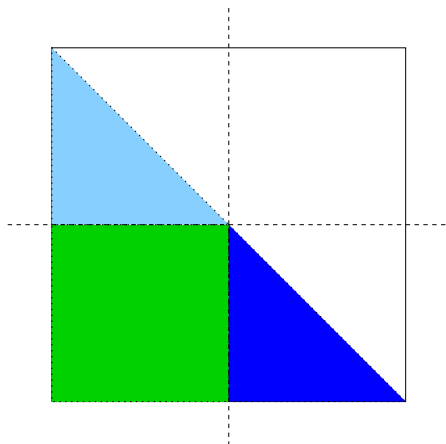
- 1 Split
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- 3 TRSM: $G \leftarrow A_{21} L_1^{-1}$

The recursive algorithm: full rank case



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- 4 SYRK: $H \leftarrow A_{22} - GG^T$

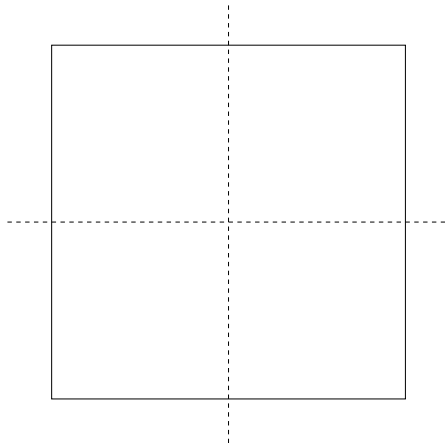
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- ⑤ Recursive call: $H = L_2 L_2^T$

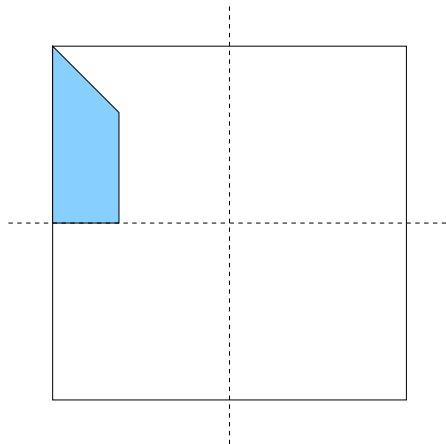
The recursive algorithm: arbitrary rank case

1 Split

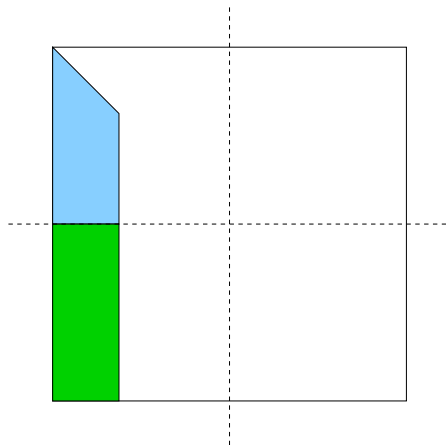


The recursive algorithm: arbitrary rank case

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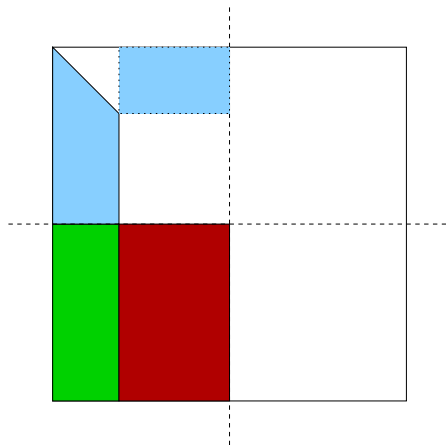


The recursive algorithm: arbitrary rank case



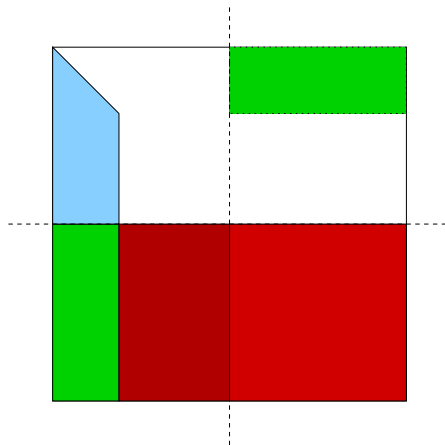
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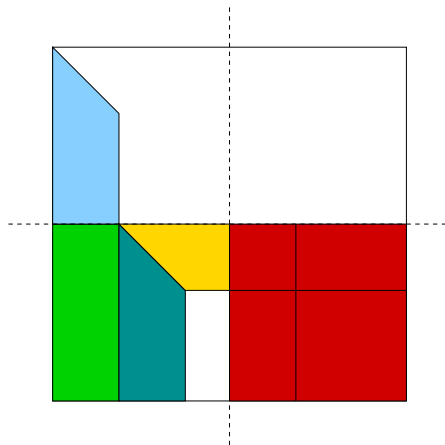
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The recursive algorithm: arbitrary rank case



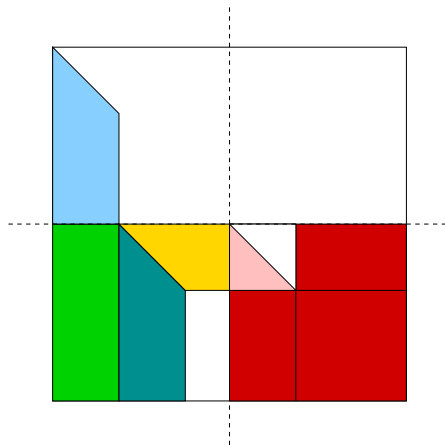
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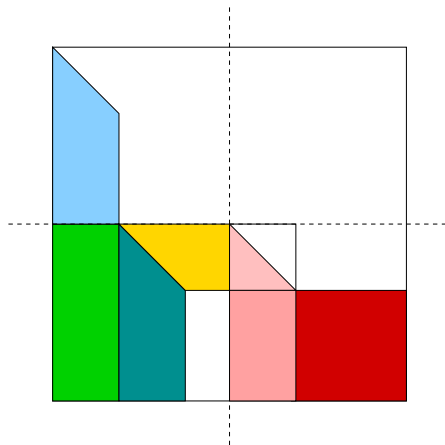
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- 6 PLUQ: $K = P_2 L_2 U_2 Q_2$

The recursive algorithm: arbitrary rank case



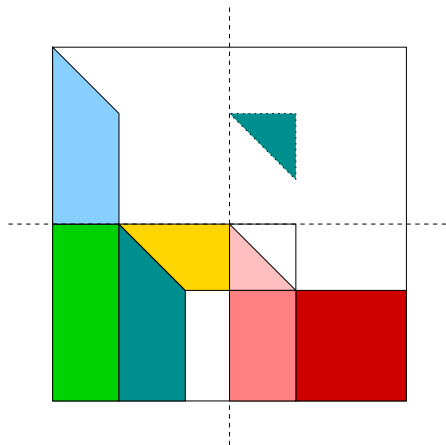
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- 6 PLUQ: $K = P_2 L_2 U_2 Q_2$
- 7 TRSYR2K: find X s.t.
 $L_2 X^T + X L_2^T = H_{11}$

The recursive algorithm: arbitrary rank case



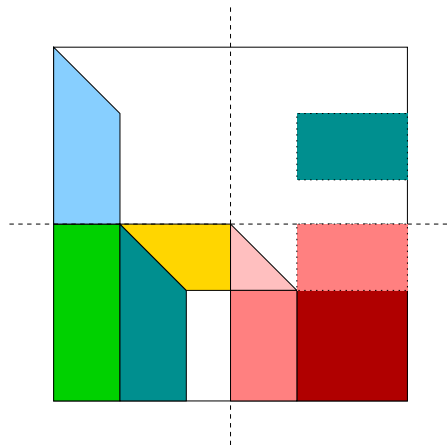
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The recursive algorithm: arbitrary rank case



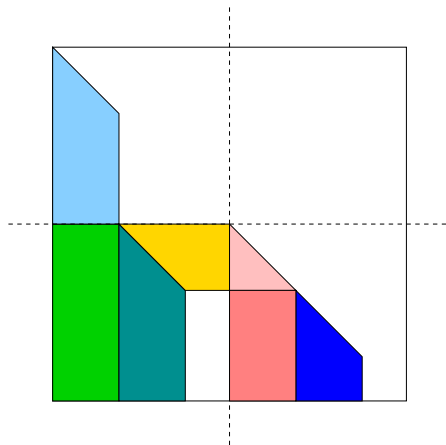
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The recursive algorithm: arbitrary rank case



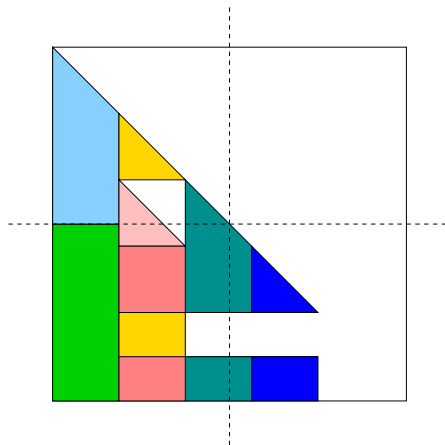
- 1 Split
- 2 Recursive call: $A_{11} = L_1 L_1^T$
- 3 TRSM: $G \leftarrow A_{21} L_1^{-1}$
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- 5 SYRK: $H \leftarrow A_{22} - G G^T$
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The trsyl2k routine

Problem

Given C symmetric and L lower triangular

Find X lower triangular such that

$$LX^T + XL^T = C$$

$$\begin{bmatrix} L_1 & \\ L_2 & L_3 \end{bmatrix} \begin{bmatrix} X_1^T & X_2^T \\ & X_3^T \end{bmatrix} + \begin{bmatrix} X_1 & \\ X_2 & X_3 \end{bmatrix} \begin{bmatrix} L_1^T & \\ & L_2^T \\ & & L_3^T \end{bmatrix} = \begin{bmatrix} C_1 & \\ & C_2 \\ & & C_3 \end{bmatrix}.$$

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$$L_1 X_1^T + X_1 L_1^T = C_1$$

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recurse

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$$L_2X_1^T + X_2L_1^T = C_2$$

① Find X_1 s.t. $L_1X_1^T + X_1L_1^T = C_1$

recurse

② $Y \leftarrow C_2 - L_2X_1^T$

trmm

③ $X_2 \leftarrow (L_1^T)^{-1}Y$

trsm

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sy2k

The trsy2k routine

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- | | | |
|---|---|---------|
| 1 | Find X_1 s.t. $L_1X_1^T + X_1L_1^T = C_1$ | recurse |
| 2 | $Y \leftarrow C_2 - L_2X_1^T$ | trmm |
| 3 | $X_2 \leftarrow (L_1^T)^{-1}Y$ | trsm |
| 4 | $Z \leftarrow C_3 - L_2X_2^T + X_2L_2^T$ | syr2k |
| 5 | Find X_3 s.t. $L_3X_3^T + X_3L_3^T = Z$ | recurse |

Problem in characteristic 2

Consider $\begin{bmatrix} 0 & c \\ c & d \end{bmatrix}$ (with $\mathcal{R} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$)

Diagonal pivoting: $\begin{bmatrix} 0 & c \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ \frac{c}{d} & 1 \end{bmatrix} \begin{bmatrix} d & \\ & -\frac{c^2}{d} \end{bmatrix} \begin{bmatrix} 1 & \frac{c}{d} \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

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- \Rightarrow off-diagonal pivoting required
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In characteristic 2

⇒ In general there is **no** RPM-revealing $P \cdot L \cdot \Delta \cdot L^T \cdot P^T$!

Characteristic 2: Preserve $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ factors

- Compute instead $A = P \cdot L \cdot D \cdot \Psi \cdot L^T \cdot P^T$:

$\Rightarrow D$ diagonal, Ψ block diagonal with 1×1 , $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ and $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ blocks

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- From this **intermediate form**:
 - Either recover $\mathcal{R}_A = P \cdot \mathcal{R}_\Psi \cdot P^T$;
 - Or use:

$$\begin{bmatrix} c & c \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & \\ c/d & 1 \end{bmatrix} \cdot \begin{bmatrix} d & \\ & -c^2/d \end{bmatrix} \cdot \begin{bmatrix} 1 & c/d \\ & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & \\ & 1 \end{bmatrix}$$

☺ + commuting

$\Rightarrow \tilde{P} \cdot \tilde{L} \cdot \Delta \cdot \tilde{L}^T \cdot \tilde{P}^T$ symmetric factorization (but \mathcal{R}_A is lost)

Iterative base case

Practical performance:

⚠ Stop recursion (less mod reductions/data move on small matrices)

Iterative base case

Practical performance:

- ⚠ Stop recursion (less mod reductions/data move on small matrices)
- ⇒ iterative base case and cascading
 - pivot search minimizing the lexicographic order
 - cyclic shifts on the row and columns
 - Crout elimination schedule

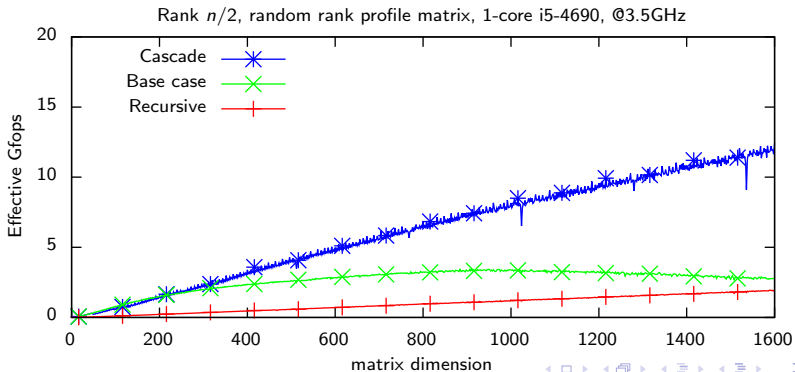
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LAPACK vs FFPACK modulo 8 388 593

n	LAPACK		FFPACK	
	dgetrf (LU)	dsytrf (LDLT)	fgetrf (LU)	fsytrf (LDLT)
5000	2.01s	1.60s	3.90s	1.59s
10000	14.95s	11.98s	24.12s	10.90s

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